

## NAG C Library Function Document

### nag\_dgelqf (f08ahc)

#### 1 Purpose

nag\_dgelqf (f08ahc) computes the  $LQ$  factorization of a real  $m$  by  $n$  matrix.

#### 2 Specification

```
void nag_dgelqf (Nag_OrderType order, Integer m, Integer n, double a[],
                 Integer pda, double tau[], NagError *fail)
```

#### 3 Description

nag\_dgelqf (f08ahc) forms the  $LQ$  factorization of an arbitrary rectangular real  $m$  by  $n$  matrix. No pivoting is performed.

If  $m \leq n$ , the factorization is given by:

$$A = (L \ 0)Q$$

where  $L$  is an  $m$  by  $m$  lower triangular matrix and  $Q$  is an  $n$  by  $n$  orthogonal matrix. It is sometimes more convenient to write the factorization as

$$A = (L \ 0) \begin{pmatrix} Q_1 \\ Q_2 \end{pmatrix}$$

which reduces to

$$A = LQ_1,$$

where  $Q_1$  consists of the first  $m$  rows of  $Q$ , and  $Q_2$  the remaining  $n - m$  rows.

If  $m > n$ ,  $L$  is trapezoidal, and the factorization can be written

$$A = \begin{pmatrix} L_1 \\ L_2 \end{pmatrix} Q$$

where  $L_1$  is lower triangular and  $L_2$  is rectangular.

The  $LQ$  factorization of  $A$  is essentially the same as the  $QR$  factorization of  $A^T$ , since

$$A = (L \ 0)Q \Leftrightarrow A^T = Q^T \begin{pmatrix} L^T \\ 0 \end{pmatrix}.$$

The matrix  $Q$  is not formed explicitly but is represented as a product of  $\min(m, n)$  elementary reflectors (see the f08 Chapter Introduction for details). Functions are provided to work with  $Q$  in this representation (see Section 8).

Note also that for any  $k < m$ , the information returned in the first  $k$  rows of the array **a** represents an  $LQ$  factorization of the first  $k$  rows of the original matrix  $A$ .

#### 4 References

None.

#### 5 Parameters

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by

**order** = **Nag\_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

*Constraint:* **order** = **Nag\_RowMajor** or **Nag\_ColMajor**.

- 2: **m** – Integer *Input*  
*On entry:*  $m$ , the number of rows of the matrix  $A$ .  
*Constraint:*  $m \geq 0$ .
- 3: **n** – Integer *Input*  
*On entry:*  $n$ , the number of columns of the matrix  $A$ .  
*Constraint:*  $n \geq 0$ .
- 4: **a**[ $dim$ ] – double *Input/Output*  
**Note:** the dimension,  $dim$ , of the array **a** must be at least  $\max(1, pda \times n)$  when **order** = **Nag\_ColMajor** and at least  $\max(1, pda \times m)$  when **order** = **Nag\_RowMajor**.  
 If **order** = **Nag\_ColMajor**, the  $(i, j)$ th element of the matrix  $A$  is stored in  $a[(j-1) \times pda + i - 1]$  and if **order** = **Nag\_RowMajor**, the  $(i, j)$ th element of the matrix  $A$  is stored in  $a[(i-1) \times pda + j - 1]$ .  
*On entry:* the  $m$  by  $n$  matrix  $A$ .  
*On exit:* if  $m \leq n$ , the elements above the diagonal are overwritten by details of the orthogonal matrix  $Q$  and the lower triangle is overwritten by the corresponding elements of the  $m$  by  $m$  lower triangular matrix  $L$ .  
 If  $m > n$ , the strictly upper triangular part is overwritten by details of the orthogonal matrix  $Q$  and the remaining elements are overwritten by the corresponding elements of the  $m$  by  $n$  lower trapezoidal matrix  $L$ .
- 5: **pda** – Integer *Input*  
*On entry:* the stride separating matrix row or column elements (depending on the value of **order**) in the array **a**.  
*Constraints:*  
     if **order** = **Nag\_ColMajor**,  $pda \geq \max(1, m)$ ;  
     if **order** = **Nag\_RowMajor**,  $pda \geq \max(1, n)$ .
- 6: **tau**[ $dim$ ] – double *Output*  
**Note:** the dimension,  $dim$ , of the array **tau** must be at least  $\max(1, \min(m, n))$ .  
*On exit:* further details of the orthogonal matrix  $Q$ .
- 7: **fail** – NagError \* *Output*  
 The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_INT

On entry, **m** =  $\langle value \rangle$ .  
*Constraint:*  $m \geq 0$ .

On entry, **n** =  $\langle value \rangle$ .  
*Constraint:*  $n \geq 0$ .

On entry, **pda** =  $\langle value \rangle$ .  
*Constraint:*  $pda > 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, \mathbf{m})$ .

On entry, **pda** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, \mathbf{n})$ .

**NE\_ALLOC\_FAIL**

Memory allocation failed.

**NE\_BAD\_PARAM**

On entry, parameter  $\langle value \rangle$  had an illegal value.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

**7 Accuracy**

The computed factorization is the exact factorization of a nearby matrix  $A + E$ , where

$$\|E\|_2 = O(\epsilon)\|A\|_2,$$

and  $\epsilon$  is the *machine precision*.

**8 Further Comments**

The total number of floating-point operations is approximately  $\frac{2}{3}m^2(3n - m)$  if  $m \leq n$  or  $\frac{2}{3}n^2(3m - n)$  if  $m > n$ .

To form the orthogonal matrix  $Q$  this function may be followed by a call to nag\_dorglq (f08ajc):

```
nag_dorglq (order,n,n,MIN(m,n),&a,pda,tau,&fail)
```

but note that the first dimension of the array **a**, specified by the parameter **pda**, must be at least **n**, which may be larger than was required by nag\_dgelqf (f08ahc).

When  $m \leq n$ , it is often only the first  $m$  rows of  $Q$  that are required, and they may be formed by the call:

```
nag_dorglq (order,m,n,m,&a,pda,tau,&fail)
```

To apply  $Q$  to an arbitrary real rectangular matrix  $C$ , this function may be followed by a call to nag\_dormlq (f08akc). For example,

```
nag_dormlq (order,Nag_LeftSide,Nag_Trans,m,p,MIN(m,n),&a,pda,
tau,&c,pdc,&fail)
```

forms the matrix product  $C = Q^T C$ , where  $C$  is  $m$  by  $p$ .

The complex analogue of this function is nag\_zgelqf (f08avc).

**9 Example**

To find the minimum-norm solutions of the under-determined systems of linear equations

$$Ax_1 = b_1 \text{ and } Ax_2 = b_2$$

where  $b_1$  and  $b_2$  are the columns of the matrix  $B$ ,

$$A = \begin{pmatrix} -5.42 & 3.28 & -3.68 & 0.27 & 2.06 & 0.46 \\ -1.65 & -3.40 & -3.20 & -1.03 & -4.06 & -0.01 \\ -0.37 & 2.35 & 1.90 & 4.31 & -1.76 & 1.13 \\ -3.15 & -0.11 & 1.99 & -2.70 & 0.26 & 4.50 \end{pmatrix} \text{ and } B = \begin{pmatrix} -2.87 & -5.23 \\ 1.63 & 0.29 \\ -3.52 & 4.76 \\ 0.45 & -8.41 \end{pmatrix}.$$

## 9.1 Program Text

```

/* nag_dgelqf (f08ahc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagf08.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, j, m, n, nrhs, pda, pdb, tau_len;
    Integer exit_status=0;
    NagError fail;
    Nag_OrderType order;
    /* Arrays */
    double *a=0, *b=0, *tau=0;

#ifdef NAG_COLUMN_MAJOR
#define A(I,J) a[(J-1)*pda + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I,J) a[(I-1)*pda + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f08ahc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[^\\n] ");
    Vscanf("%ld%ld%ld%*[^\\n] ", &m, &n, &nrhs);

#ifdef NAG_COLUMN_MAJOR
    pda = m;
    pdb = n;
#else
    pda = n;
    pdb = nrhs;
#endif

    tau_len = MIN(m,n);

    /* Allocate memory */
    if ( !(a = NAG_ALLOC(m * n, double)) ||
        !(b = NAG_ALLOC(n * nrhs, double)) ||
        !(tau = NAG_ALLOC(tau_len, double)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A and B from data file */
    for (i = 1; i <= m; ++i)
    {
        for (j = 1; j <= n; ++j)
            Vscanf("%lf", &A(i,j));
    }
    Vscanf("%*[^\\n] ");
    for (i = 1; i <= m; ++i)

```

```

    {
        for (j = 1; j <= nrhs; ++j)
            Vscanf("%lf", &B(i,j));
    }
Vscanf("%*[^\\n] ");

/* Compute the LQ factorization of A */
f08ahc(order, m, n, a, pda, tau, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f08ahc.\\n%s\\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Solve L*Y = B, storing the result in B */
f07tec(order, Nag_Lower, Nag_NoTrans, Nag_NonUnitDiag, m,
        nrhs, a, pda, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07tec.\\n%s\\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Set rows (M+1) to N of B to zero */
if (m < n)
{
    for (i = m + 1; i <= n; ++i)
    {
        for (j = 1; j <= nrhs; ++j)
            B(i,j) = 0.0;
    }
}

/* Compute minimum-norm solution X = (Q**T)*B in B */
f08akc(order, Nag_LeftSide, Nag_Trans, n, nrhs, m, a, pda,
        tau, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f08akc.\\n%s\\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print minimum-norm solution(s) */
x04cac(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs, b, pdb,
        "Minimum-norm solution(s)", 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04cac.\\n%s\\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
if (a) NAG_FREE(a);
if (b) NAG_FREE(b);
if (tau) NAG_FREE(tau);
return exit_status;
}

```

## 9.2 Program Data

f08ahc Example Program Data

4	6	2					:Values of M, N and NRHS
-5.42	3.28	-3.68	0.27	2.06	0.46		
-1.65	-3.40	-3.20	-1.03	-4.06	-0.01		
-0.37	2.35	1.90	4.31	-1.76	1.13		
-3.15	-0.11	1.99	-2.70	0.26	4.50	:End of matrix A	
-2.87	-5.23						
1.63	0.29						
-3.52	4.76						
0.45	-8.41					:End of matrix B	

### 9.3 Program Results

f08ahc Example Program Results

```
Minimum-norm solution(s)
      1      2
1      0.2371      0.7383
2     -0.4575      0.0158
3     -0.0085     -0.0161
4     -0.5192      1.0768
5      0.0239     -0.6436
6     -0.0543     -0.6613
```

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